VIPUL RAMTEKKAR

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Interests _



- · Computer Vision, Machine Learning, Deep Learning, Robotics
- **Key Courses**: Machine Learning, Deep Learning and Practices, Reinforcement Learning, Medical Image Computing, Optimization, Operating Systems, Data System and Security, Data Structure and Algorithms, Logic in CS

EDUCATION _

Indian Institute of Technology Bombay

Bachelor of Technology, Department of Chemical Engineering

July 2016 - June 2020

Mumbai, India

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• **GPA**: 8.81/10.0

• Minor Degree: Computer Science and Engineering

Industrial Research Experience _

Computer Vision Research Engineer | Honda Research & Development, Japan Robot Development, Honda Life Creation

Winter 2020 - Present Tokyo, Japan

- Working on detection, path prediction & avoidance of dynamic obstacles in intersections and narrow roads
- Working on path planning in intersection crossing using deep neural network model predictive control; Performing analysis in custom CARLA world & scenarios with localization and perception noises to increase robustness
- · Working on building visual navigation and tracking along with trajectory prediction for mobile robots
- Worked on building a **semantic elevation module**, an end-to-end vision module which incorporates point cloud data and visual information to generate **high quality costmap** to enable traversability in **highly dynamic environment**
- Conducted benchmarking of **trajectory planning & speed algorithms** to evaluate their efficiency. Performed error analysis by **introducing noise** into perception, localization, and control signals to assess the robustness of the systems
- Built a model for semantic segmentation in highly uneven terrain with SOTA accuracy by reducing class imbalance
- Worked in collaborative research with leading universities to improve perception for autonomous robots
- Achieved drastic improvement in the performance of semantic segmentation in adverse environment by developing novel framework to utilise the synthetic images using Deep Generative Models to bridge the domain gap
- Implemented localization and vision nodes in ROS 2 for robust and fast performance in uncertain environments

ACADEMIC RESEARCH EXPERIENCE _

Video Object Tracking in UAVs | University of Missouri-Columbia, USA Prof. Kannappan Palaniappan, Electrical Engineering & Computer Science Dept [LOR]

Summer 2019 MU, USA

- Worked in **collaborative research** with the **US Army Research Lab** on embedded software and algorithm development for computer vision and machine learning applications for **Autonomous Unmanned Aerial Vehicle**
- Developed state-of-art video object tracker with 67% higher robustness & accuracy compared to current trackers by fusing siamese deep network with motion flux and YOLO object detection for low-power embedded processing systems
- Worked on enhancing the tracking speed of **Spatial Pyramid Context Aware Tracker** by leveraging its multi-feature extractor and adding a deep learning component to it to achieve persistent detection and tracking of vehicles
- Developed a python based tool to analyse trackers and benchmarked them based on their accuracy and robustness

Transposon Classifier | University of Tokyo, Japan Prof. Shinichi Morishita, Computational Biology Dept

Summer 2018 UTokyo, Japan

- Proposed a model to identify transposable elements by training a Support Vector Machine classifier with cosine similarity kernel. Achieving a **1.2x better** accuracy and **10x better** training time compared to the traditional classifier
- Implemented algorithms for sequence alignment and created data visualisations using JavaScript and D3 library
- Showcased the research project in the IIT Bombay's Research and Technology Symposium, ResTech 2018

Major Projects .

Computer Vision Head | SeDriCa, Self Driving Car | UMIC IIT Bombay Prof. Amit Sethi, Electrical Engineering Dept

Autumn 2018 - Spring 2020 IIT Bombay

- Leading a team of four students to implement various deep learning methods for object detection, object classification and image segmentation of the acquired visual input from the vehicle to achieve level 4 autonomy
- Amongst the top 11 teams out of 259 to be awarded Mahindra e2o car for the Mahindra Rise Driverless Car Challenge
- Implemented (in tensorflow) and analysed various encoder-decoder based CNN architectures for image segmentation
- Developed various python based tools to annotate, correct and remove incorrect instances from the datasets [news]

Chief Engineer | Matsya, Autonomous Underwater Vehicle (AUV)

Prof. Leena Vachhani, System and Control Dept

RoboSub, AUVSI & US Office of Naval Research

Autumn 2016 - Spring 2018

- Designed and developed a state-of-the-art unmanned **Autonomous Underwater Vehicle (AUV)** that localises itself and performs realistic missions based on feedback from visual, inertial, acoustic and depth sensor using thrusters/propellers
- Achieved 2nd position in the world in Robosub 2016 amongst 44 teams from 10 different countries and National Winner of Student AUV Competition, SAVe 2017, conducted by the National Institute of Ocean Technology (NIOT)
- Optimised and implemented design of pneumatically driven 2-DOF gripper picking a wide range of geometrical objects and enhanced the torpedo's design to create a locking mechanism for better pressure buildup
- Represented the team in various tech and research expositions and conducted interviews for the team recruitment [video]

- Designed a bot which costs 84% lower than annual labour cost & picks strawberries 6x faster than manual picking
- Retrained a tiny yolo classifier with **transfer learning** to detect strawberries using Fruit-360 dataset and performed image augmentation using various computer vision methods like histogram equalization and linear transformations
- Awarded Bronze Medal based on prototype and pitch of the business model to a panel of professors and investors

User Mimicking ChatBot

Autumn 2018

Prof. P Balamurugan, Industrial Engineering and Operations Research Dept

IIT Bombay

- Created a chatbot by using a Sequence to Sequence Model that learns to converse like the user inspired from the popular show Black Mirror by training on his/her data from various social media accounts like Facebook, WhatsApp & LinkedIn
- Improved the model by adding Cornell Movie-Dialogs Corpus and used adaptive optimizers to reduce training time

Autonomous Sanitation and Cleanliness Bot

Autumn 2017-Winter 2017 IIT Madras

Inter-IIT Technical Meet

- Designed a state of the art, light weight & compact toilet cleaning bot with 1-DOF arm to clean stains and a rotation flap to pick trash. Minimized the cost by 57% and improved the cleaning time by 2.5x against manual controlled machines
- Trained a Haar Cascade Classifier to detect the toilet, and detected the stains and trash using edge detection and colour thresholding, implemented communication between arduino & raspberry pi using pySerial to establish arm control

SCHOLASTIC ACHIEVEMENTS _

- Selected for HPAIR'19 conference at Havard University in Cambridge, Massachusetts from a pool of 10,000+ applicants
- Awarded an Academic Proficiency grade (Top 1%) for performing exceptionally well in Solid Mechanics
- ullet Recipient of the \mathbf{UTSIP} Scholarship and JST Travel Fund to pursue research in University of Tokyo, Japan
- Awarded the Institute Technical Color for exceptional contribution towards the growth of tech in the Institute

TECHNICAL SKILLS _

Programming

Python, C/C++, JavaScript, Java, HTML

Frameworks & Tools

Pytorch, Tensorflow, JAX, Keras, OpenCV, Matlab, LATEX, Git, ROS

Positions of Responsibility

- Editorial Board Member | Insight | Official Student Media Body of IIT Bombay Spring 2019 Spring 2020 1 of the 20 editors heading 200+ journalists | 160+ articles | 50+ videos | 350k+ web views | 1.5 million+ online reach
 - Spearheading myriad of projects like analyzing research in the institute, reportage and worked on various initiatives like University Series blogs to help students make a more informed decision for graduate & post graduate programs
 - o Surveyed 10k+ students to understand their inclination towards politics during the 2019 Lok Sabha elections
- Academic Mentor | Department Academic Mentorship Program

Spring 2018 - Spring 2020

- \circ Selected as a Mentor (1/24 of 108) based on academics, ethics and peer reviews to guide sophomores to accelerate their performance by leveraging the resources in the department and to help them cope with the curriculum
- Assisting academically weak students clear their backlogs by closely monitoring their performance & progress

Extracurriculars _____

- Ranked 4th out of 92 teams from IITB at WorldQuant's International Quant Challenge-Stage 1 [2019]
- Achieved 2nd position in Scientific Computation Blitz Competition participated by students institute-wide

[2018]

• Ranked 1st in Stock Market Game conducted by E-Cell, IIT Bombay in which 50+ teams participated

[2016]

• Completed 80+ hours social work under NSS which involved conducting events for underprivileged children in collaboration with different NGOs and spreading awareness regarding various social issues

[2016-17]

• Hobbies: travelling (200+ cities in 10 countries spread across four continents), trekking, reading and chess